

Books

1. Birglen, L., Laliberté, T. and Gosselin, C., 2008, *Underactuated robotic hands*, Springer Tracts in Advanced Robotics, Vol. 40, Springer, 244 pp.
2. Kong, X. and Gosselin, C., 2007, *Type synthesis of parallel mechanisms*, Springer Tracts in Advanced Robotics, Vol. 33, Springer, 280 pp.

Articles in refereed journals

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2. Gosselin, C., Laliberté, T. and Veillette, A., 2015, 'Singularity-free kinematically redundant planar parallel mechanisms with unlimited rotational capability', *IEEE Transactions on Robotics*, Vol. 31, No. 2, pp. 457–467.
3. Zhang, M. and Gosselin, C., 2015, 'Optimal design of safe planar manipulators using passive torque limiters', to appear in the *ASME Journal of Mechanisms and Robotics*.
4. Lauzier, N. and Gosselin, C., 2015, 'A comparison of the effectiveness of different approaches for the design of human-friendly robots', to appear in the *ASME Journal of Mechanical Design*.
5. Barnett, E. and Gosselin, C., 2015, 'Weak support material techniques for alternative additive manufacturing materials', To appear in *Additive Manufacturing*.
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