FORMAT: # (single numbers) or [#,#] (intervals)

5. Specify the required wrench set

Notation	Meaning	Valid Entries:
F_x	External Forces on Platform	Values should be real (whole/decimal and positive/negative/zero) numbers
F_y		
F_z		
M_x	External Moments on Platform	Values should be real (whole/decimal and positive/negative/zero) numbers
M_y		
M_z		

Note: For the *planar case*, the required wrench set should be specified according to the type of planar robot introduced, the other fields may be left with or without entries since ARACHNIS only processes each case specific entries. (For example for a robot in the XY plane, a required wrench set consisting F_x, F_y, M_z should be specified.)

For the *spatial case* all task parameters should be specified.